#### **Optimal Scaling of MCMC Algorithms**

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#### What is Optimal Scaling?

• Gareth Roberts' work: Random walk Metropolis and Langevin Algorithm

- Hybrid Monte Carlo Algorithm
- Optimal Scaling in Infinite Dimensions
- Conclusion

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- Seminal paper: Roberts, Gelman and Gilks, 1997. (1000 citations)
- Target density: i.i.d components

$$\pi^N(x) = \prod_{i=1}^N f_i(x_i) \propto \prod_{i=1}^N e^{-g_i(x_i)}$$

• Simple Random walk Proposal:

$$y = x + \sqrt{\ell \,\delta} Z_N$$

- $Z_N \sim No(0, I_N)$ .
- $\ell$  "optimisation" parameter.
- $\delta = \delta(N)$  is the SCALE.

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### Traditionally, ....

- Study of Mixing times
- Time to attain Stationarity
- 'Burn in time'
- Spectral gap

Hard problems ...

For practical MCMC arguably optimisation questions (find the best algorithm from a class) are more important

# The new perspective in Roberts, Gelman and Gilks, 1997

- Study the Markov chain AFTER Stationarity
  - thus complementing work on convergence, robustness to starting values etc..

- Scale the proposal as a function of the dimension.
- Goldilocks Principle (attributed to Rosenthal, J.)

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- Scale the proposal as a function of the dimension.
- Goldilocks Principle (attributed to Rosenthal, J.)

- Acceptance Probability = min $(1, \frac{\pi(y)}{\pi(x)})$ .
- If y ≈ x, π(y) ≈ π(x), and thus acceptance probability is equal is very high.

• If y is far away from x, then  $\frac{\pi(y)}{\pi(x)} \ll 1!$ 

## Goldilock's Principle; Figure courtesy: Roberts and Rosenthal, 2001.



FIG. 2. Simple Metropolis algorithm with (a) too-large variance (left plots), (b) too-small variance (middle) and (c) appropriate variance (right). Trace plots (top) and autocorrelation plots (below) are shown for each case.

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Choose the scale such that

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\mathbb{E}(\text{acc prob}) = \mathcal{O}(1)
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• For large *N*,

$$\mathbb{E}(\mathsf{acc} \mathsf{ prob}) = a(N) \approx a$$

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• Optimise a, to obtain "best" acceptance probability.

#### Roberts, Gilks and Gelman, 1997:

Theorem: (for distributions with exponential moments + mild conditions)

• 
$$\delta = \delta(N) = \frac{1}{N}$$
.

• A SINGLE component (rescaled) :  $x^k \Rightarrow X_t$ 

$$dX_t = -h(\ell) \nabla g(X_t) dt + \sqrt{2h(\ell)} \, dW_t$$

• 
$$\mathbb{E}(\operatorname{acc}\operatorname{prob}) o 2\Phi(-rac{\ell}{\sqrt{2}})$$

• Expected Squared Jumping Distance:

$$h(\ell) = \mathbb{E}(x^{k+1} - x^k)^2 \to 2\ell^2 \Phi(-\frac{\ell}{\sqrt{2}})$$

• Optimal acceptance probability: Maximizes the expected squared jumping distance:

$$\hat{a} = 0.234$$

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### Optimal Acceptance Probability; Figure courtesy: Roberts and Rosenthal, 2001



FIG. 5. Convergence times for Metropolis algorithms as a function of their acceptance rates. The plotting symbol indicates the dimension of the simulation.

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- Why maximize  $\mathbb{E}(x^{k+1} x^k)^2$ ?
- At stationarity

$$\mathbb{E}(x^{k+1} - x^k)^2 = \mathbb{E}(x^{k+1})^2 + \mathbb{E}(x^k)^2 - 2\operatorname{Cov}(x^{k+1}, x^k)$$
  
=  $2M - 2\operatorname{Cov}(x^{k+1}, x^k)$ 

- Why only lag-1 correlation? Higher orders?
- The quantity  $h(\ell)$  is the Speed of the diffusion.
- Thus, because of the diffusion limit, maximizing *h*(*l*) leads to minimizing the asymptotic variance.

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Suppose we want to estimate  $\int f(u)\pi(du)$ .

• Given the precision  $\epsilon$ , find T and compute

$$\widehat{f} = \frac{1}{T} \int f(X_t) dt$$

• Diffusion Limit + Optimal Scaling implies that

$$\widehat{f}_N = rac{1}{T}\sum_{k=1}^{\lfloor T/\delta 
floor} f(X_k) \qquad \delta = O(N^{-1})$$

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has the same precision as  $\hat{f}$ .

• The mixing time of the RWM is O(N).

- Recall Langevin diffusion:  $dx_t = -\nabla g(x_t)dt + \sqrt{2}dW_t$ .
- Langevin Proposal:

$$y = x - \nabla g(x)\ell\,\delta + \sqrt{2\ell\,\delta}Z_N$$

- Need a Metropolis Accept/Reject mechanism.
- $x^k$  is the Langevin Markov chain on  $\mathbb{R}^N$  for iid target.
- Theorem (Roberts + Rosenthal 1998): The scale is δ(N) = N<sup>-1/3</sup> and after rescaling the first component of the Markov chain {x<sup>k</sup>} converges in distribution to X<sub>t</sub>:

$$dX_t = -h_1(\ell) \nabla g(X_t) dt + \sqrt{2h_1(\ell)} dW_t .$$

• Optimal Acceptance Probability = 0.574.

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- Recall RWM had complexity of O(N)
- Langevin has complexity of  $O(N^{1/3})$ .
- Thus optimal scaling gives a nice way to compare algorithms.
#### So far:

- Summary:
  - optimal scaling: tuning proposals.
  - Diffusion limits for RWM and Langevin

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• Hybrid Monte Carlo Algorithm

• Infinite Dimensional Result

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Hybrid Monte Carlo Algorithm

• Infinite Dimensional Result

#### So far:

- Summary:
  - optimal scaling: tuning proposals.
  - Diffusion limits for RWM and Langevin

- Hybrid Monte Carlo Algorithm
- Infinite Dimensional Result

- Algorithm from Physics, (Duane et. al. (1987))
- Based on Hamiltonian Dynamics, conservation of energy.

Location x, velocity v; total energy,

$$H(x,v)=g(x)+\frac{1}{2}v^2$$

Hamiltonian equations

$$\frac{dx}{dt} = v; \ \frac{dv}{dt} = -\nabla g(x)$$

They give rise to solution operator

 $\phi^{\mathsf{T}}:(\mathbf{x}_0,\mathbf{v}_0)\mapsto(\mathbf{x}_{\mathsf{T}},\mathbf{v}_{\mathsf{T}})$ 

that preserves total energy.

• Equivalently the joint density

$$\exp\{-H(x,v)\} = \exp\{-g(x) - \frac{1}{2}v^2\}$$

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In practice, dynamics are approximated:

$$\phi^T \approx \phi^{T,h} \; .$$

• For initial state (*x*<sub>0</sub>, *v*<sub>0</sub>): Leapfrog Discretisation,

$$egin{aligned} & v_{h/2} = v_0 - rac{h}{2} \, 
abla g(x_0) \ & x_h = x_0 + h \, v_{h/2} \ & v_h = v_0 - rac{h}{2} \, 
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- $\phi^{T,h}$  is obtained by composing  $\frac{T}{h}$  leapfrog steps.
- The crucial properties of this approach are that it is volume preserving and reversible.

- $(x_0, v_0)$  : Initial position
- $(x_T, v_T)$ : Final position
- Accept with probability

#### $1 \wedge \exp\{H(x_0, v_0) - H(x_T, v_T)\}$

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• Acceptance probability = 1, if Hamilton's Differential Equations can be solved explicitly.

- $(x_0, v_0)$  : Initial position
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 Acceptance probability = 1, if Hamilton's Differential Equations can be solved explicitly. "Although HMC has been found useful for Bayesian computations, many important issues remain open. For example, how to choose tuning parameters in HMC, e.g., the step-size and the number of the leapfrog iterations, is still a difficult problem. A rule of thumb is to maintain an acceptance rate of nearly 70%. But there seems to be no clear theoretical basis for this rule. "

#### Main result

- P., Beskos, Roberts, Sanz-Serna, Stuart, 2013.
- Target density

$$\pi^N(x) = \prod_{i=1}^N e^{-g_i(x_i)}$$

- Theorem : For any fixed integration length *T*, the step size which maximizes the expected squared distance :
   h = h(N) = <sup>1</sup>/<sub>N<sup>1/4</sup></sub>.
- For any Fixed integration length T, optimal scaling leads to a complexity of  $O(N^{1/4})$ .
- For any Volume preserving, time reversible second order numerical integrator, the optimal acceptance probability is 0.651.

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### HMC, the optimal behavior is not Diffusive! The complexity of HMC is O(N<sup>1</sup>/<sub>4</sub>).

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#### This first result was proved for IID targets only.

- Empirically seen to be robust well beyond IID case!
- What are the challenges for the Non-Product case?
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- Let *H* be an infinite dimensional Hilbert space, *π*<sub>0</sub> ~ N(0, *C*).
- Our target measure:

$$\pi(f) \propto \exp\{-\Psi(f)\}\pi_0(f)$$

• For *N* large, we take *N* dimensional projection:

$$\pi^N \approx \pi$$

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•  $\pi$  is **NOT** a product measure.

#### • $\mathcal{H}$ Hilbert space, $\pi_0 \sim N(0, C)$ .

• Target:

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- Diffusion bridges. (Girsanov)
- Constructive Quantum Field Theory,  $P(\phi_2^4)$  model.

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• Recall *f* is a function, target  $\pi$  measure on  $\mathcal{H}$ .

$$\pi(f) \propto \exp\{-\Psi(f)\} \pi_0(f), \qquad \pi_0(f) \sim \mathsf{No}(0, \mathcal{C})$$

- Proposal  $y = x + Z_N$ ,  $Z_N \sim No(0, C^N)$ . Mattingly, P., Stuart (Annals of App. Prob., 2012)
- $\{x^k\}$  is the Random Walk Metropolis Markov chain on  $\mathbb{R}^N$ .
- Theorem: For the scaling  $\delta(N) = \frac{1}{N}$  the (rescaled) Markov chain  $\{x^k\}$  converges in distribution to an infinite dimensional diffusion (SPDE)  $X_t$

$$dX_t = (-X_t - C\nabla\Psi(X_t))dt + \sqrt{2C} \, dW_t.$$

- Weak Convergence in  $C([0, T], \mathcal{H})$ .
- Optimal Acceptance Probability = 0.234.

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#### Weak Convergence to SPDE: Proof Sketch

• Decompose the Markov Chain into Drift + Noise

$$x^{k+1} = x^k + \mathbb{E}(x^{k+1} - x^k | x^k) + \sqrt{2\ell\delta} \, \Gamma^k$$

• Obtain Drift and Diffusion Estimates

$$\mathbb{E}(x^{k+1} - x^k | x^k) \approx -\nabla \Psi(x^k) \,\delta$$

- Martingale Central Limit Theorem, noise satisfies an invariance principle.
- Continuity of the Ito map :  $\Theta$  :  $C([0, T], \mathcal{H}) \mapsto C([0, T], \mathcal{H})$ ,  $\Theta(W) = X$ :

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- Combining behavior at transience + behavior at stationarity.
- Recall that, at stationarity, the scaling for Langevin is  $N^{-1/3}$ .
- For RWM, Langevin, before reaching stationarity, the scaling is N<sup>-1</sup> (O.F. Christensen, G.O. Roberts, and J.S. Rosenthal, 2003.)

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- For RWM, Langevin, before reaching stationarity, the scaling is N<sup>-1</sup> (O.F. Christensen, G.O. Roberts, and J.S. Rosenthal, 2003.)

Optimal scaling is an important idea, with deep practical implications.

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- Lots more to do!
- "Dimension" can be different things.

Thanks to:

- Gareth O. Roberts
- Jeffrey S. Rosenthal
- Organizers + Applied Probability Society

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